

* Fourier transform (Delta function) :-

$$F\{1\} = \delta(f)$$

$$\delta(f) = \int_{-\infty}^{\infty} e^{-j2\pi ft} dt$$

Ex. $F\{e^{j2\pi f_c t}\}$

$$= \int_{-\infty}^{\infty} g(t) e^{-j2\pi ft} dt$$

$$= \int_{-\infty}^{\infty} e^{j2\pi f_c t} e^{-j2\pi ft} dt$$

$$= \int_{-\infty}^{\infty} e^{-j2\pi (f-f_c)t} dt$$

$$= \delta(f-f_c)$$

* Ex:- Find Fourier transform of $g(t) = \cos 2\pi f_c t$

$$g(t) = \frac{1}{2} (e^{j2\pi f_c t} + e^{-j2\pi f_c t})$$

$$\therefore F\{\cos(2\pi f_c t)\} = \frac{1}{2} F\{e^{j2\pi f_c t}\} + \frac{1}{2} F\{e^{-j2\pi f_c t}\}$$

$$= \frac{1}{2} \delta(f-f_c) + \frac{1}{2} \delta(f+f_c)$$

$$= \frac{1}{2} \{\delta(f-f_c) + \delta(f+f_c)\}$$

* Ex : Compute $F \{ 2 \sin(2\pi f_c t) \}$

$$\begin{aligned} \therefore F \{ 2 \sin(2\pi f_c t) \} &= \frac{1}{j} e^{j2\pi f_c t} - \frac{1}{j} e^{-j2\pi f_c t} \\ &= \frac{1}{j} \delta(f - f_c) - \frac{1}{j} \delta(f + f_c) \end{aligned}$$

problem :

Compute Fourier transform of :

1) $g(t) = 2 \sin^2(2\pi f t)$

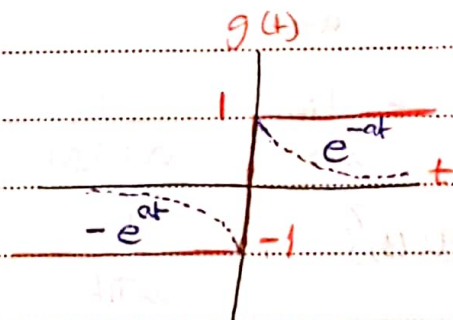
2) $g(t) = 3 \sin^2(4\pi f t)$

3) $g(t) = \cos^2(2\pi f t)$

* Example : $F \{ \text{sgn}(t) \}$

$$g(t) = \text{sgn}(t)$$

$$= \begin{cases} 1, & t \geq 0 \\ -1, & t < 0 \end{cases}$$



$$F \{ e^{-at} u(t) \} = \frac{1}{a + j2\pi f}$$

$$F \{ -e^{-at} u(t) \} = \frac{-1}{a - j2\pi f}$$

$$\therefore \frac{1}{a + j2\pi f} - \frac{1}{a - j2\pi f} = \frac{a - j2\pi f - a - j2\pi f}{(a + j2\pi f)(a - j2\pi f)}$$

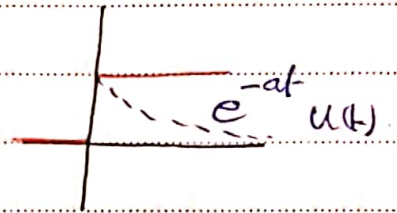
$$= \frac{-j4\pi f}{a^2 + (2\pi f)^2}$$

$$i. F \{ \text{sgn}(t) \} = \lim_{a \rightarrow 0} \left[\frac{-j4\pi f}{a^2 + (2\pi f)^2} \right]$$

$$= -j2 \cdot \frac{2\pi f}{(2\pi f)^2} = \frac{-j2}{2\pi f} = \frac{-j}{\pi f} = \frac{1}{j\pi f}$$

* $g(t) = u(t)$

$$= \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$



$$F \{ u(t) \} = F \{ e^{-at} u(t) \}$$

$$= \lim_{a \rightarrow 0} \frac{1}{a + j2\pi f}$$

* $i. F \{ u(t) \} = \frac{1}{j2\pi f}$ *

Fourier Transform :- For aperiodic signal.
Fourier Series :- For periodic signal.

1) low pass filter (LPF).

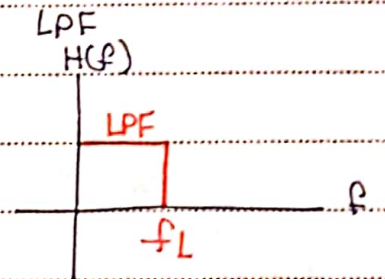
2) High pass filter (HPF).

3) Band pass filter (BPF).

4) Band stop filter (BSF).

LPF :-

This filter lets all signals that have frequencies in the range $0 \leq f \leq f_L$ to pass through this filter.



* Example :-

Let we have a LPF with $f_L = 20 \text{ kHz}$. Check which of the following signals can pass through the filter?

1) $x(t) = 3 \cos 30000\pi t$

2) $y(t) = 8 \sin 50000\pi t$

3) $z(t) = 8 \sin^2 25000\pi t$

4) $w(t) = 2 \cos 30000\pi t - 8 \sin 30000\pi t$

Solution :-

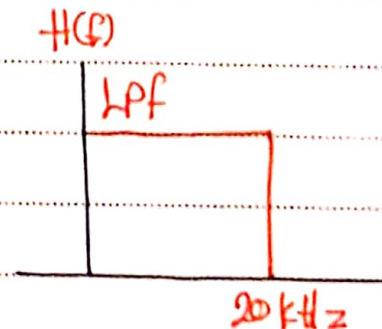
1) $x(t) = 3 \cos 30000\pi t$

$\rightarrow -H(f) = \cos 2\pi f t$

$\rightarrow = \cos 2(15 \text{ kHz})\pi t$

$0 < 15 \text{ kHz} < f_L = 20 \text{ kHz}$

$\rightarrow$ This filter can pass from the filter



$$\begin{aligned} 2) y(t) &= \sin 50000 \pi t \\ &= \sin (25 \text{ kHz}) 2\pi t \\ 25 \text{ kHz} &> f_L \end{aligned}$$

∴ The LPF will filter out the signal.

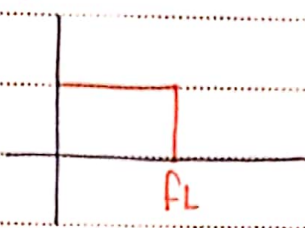
$$\begin{aligned} 3) z(t) &= \sin^2 25000 \pi t \\ &= \frac{1}{2} + \frac{1}{2} \sin 2\pi (2f) t \\ &= \frac{1}{2} + \frac{1}{2} \sin 2\pi (50 \text{ kHz}) t \\ &= \underbrace{\frac{1}{2}}_{\text{DC value}} + \underbrace{\frac{1}{2} \sin 2\pi (50 \text{ kHz}) t}_{\text{AC with } f = 50 \text{ kHz}} \end{aligned}$$

$f = 0 \text{ Hz}$

$$\begin{aligned} 4) w(t) &= 2 \cos 30000 \pi t \sin 3000 \pi t \\ &= \sin 60000 \pi t \\ &= \sin 2\pi t (30 \text{ kHz}) \\ 30 \text{ kHz} &> f_L \end{aligned}$$

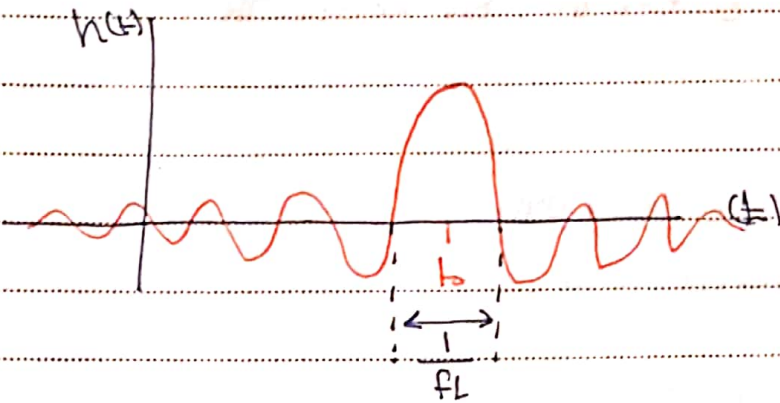
∴ This signal is filtered out.

$H(f)$



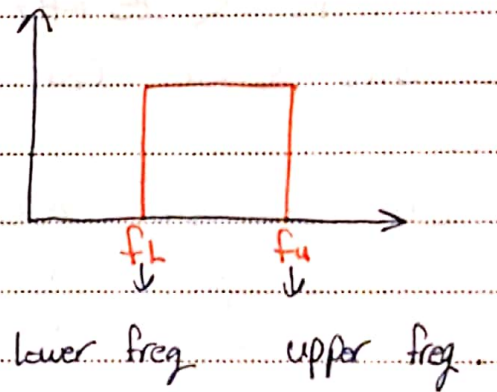
$$H(f) = \begin{cases} e^{-j2\pi f t_0} & -f_L \leq f \leq f_L \\ 0 & \text{o.w} \end{cases}$$

$$h(t) = 2f_L \text{sinc}(2f_L(t-t_0))$$



#BPF :-

Band pass filter will let all signals that have frequencies between f_L and f_u to pass.



* Example :-

let we have BPF with frequency $f_L = 20 \text{ kHz}$, $f_u = 40 \text{ kHz}$, check which of the following signals can pass through the filter?

$$1) H(t) = 3 \cos 30000 \pi t$$

$$2) y(t) = 8 \sin 50000 \pi t$$

$$3) Z(t) = \sin^2 25000 \pi t$$

$$4) W(t) = 2 \cos 30000 \pi t \sin 30000 \pi t$$

Solution :-

$$1) H(t) = 3 \cos (15 \text{ kHz}) 2\pi t$$

$\therefore$ it will be filtered out.

$$2) y(t) = 8 \sin (25 \text{ kHz}) 2\pi t$$

$$f_L < 25 \text{ kHz} < f_u$$

$\therefore$ This signal can pass from this filter.

$$3) Z(t) = \sin^2 25000 \pi t$$

$$= \frac{1}{2} + \frac{1}{2} \sin 50000 \pi t$$

AC value

$$f = 0 \text{ Hz}$$

DC value

$$f = 25000 \text{ Hz}$$

$$4) W(t) = 2 \cos 30000 \pi t \sin 30000 \pi t$$

$$= 8 \sin 60000 \pi t$$

$\therefore$ Can pass through the filter.